## CSCI 5521: Pattern Recognition

## Please submit your work in an electronic document with a standard readable format (e.g. pdf, rtf, doc, txt). All matlab code should be put into a separate file that is executable as a script or function.

## Problem set 1

## Due: 9/20/07 Midnight

Download the file arrow.m:
http://www.mathworks.com/matlabcentral/fileexchange/loadFile.do?objectId=278\&objectType=file
Use the arrow command to visualize vectors.

1. $(10 \%)$ Consider the vectors $x_{1}=[1,0]^{T} ; \quad x_{2}=\left[1, \frac{1}{\sqrt{2}}\right]^{T}$; Compute the area formed by the parallelogram of these two vectors using the formula for the area of a right triangle Area $=\frac{1}{2}\left(\right.$ base ${ }^{*}$ height $)$. Now put the two vectors into a matrix A, and compute the determinant. What is the relationship between $\operatorname{det}(\mathbf{A})$ and area? What if either one or both $x_{i}$ is negated? Now let
$x_{1}=[0.86603,0.5]^{T} ; \quad x_{2}=[0.51247,1.11237]^{T}$; Again use the right triangle formula and the determinant to determine the area (it may help to visualize using arrow.m) and the $\operatorname{det}()$. Can you find a relationship between these two formulae?
2. $(20 \%)$ Consider the equation $\vec{y}=A \vec{x} \Rightarrow\left[\begin{array}{l}y_{1} \\ y_{2}\end{array}\right]=\left[\begin{array}{l}b_{1}^{T} \\ b_{2}^{T}\end{array}\right]\left[\begin{array}{l}x_{1} \\ x_{2}\end{array}\right]$

Let
$b_{1}=\left[\begin{array}{c}-\sqrt{3} / 4 \\ \frac{1}{4}\end{array}\right] ; \quad b_{2}=\left[\begin{array}{c}\sqrt{3} / 4 \\ \frac{1}{4}\end{array}\right] ;$
Using Matlab, plot the constraint lines determined by $b_{1}$ and $b_{2}$ for the range $-4: 4$, i.e. determine the lines perpendicular to $b_{1}$ and $b_{2}$ such that the dot product between the $b_{i}$ and any other vector is equal to $\{-4,-3,-2, \ldots, 4\}$ for each $b_{i}$, and display them using the line() command or the $\operatorname{plot}()$ command. Graphically solve for x when $\left[\begin{array}{l}y_{1} \\ y_{2}\end{array}\right]=\left[\begin{array}{l}-1 \\ -1\end{array}\right]$. Use matrix inversion to solve for x .
3. $(20 \%)$ Let $x$ and $y$ be identically Gaussian random variables:

$$
\begin{aligned}
& p(x)=N\left(\mu, \sigma_{x}\right)=\frac{1}{\sqrt{2 \pi \sigma_{x}}} \exp \left(-\frac{1}{2} \frac{(x-\mu)^{2}}{\sigma_{x}^{2}}\right) \\
& p(y \mid x)=N\left(x, \sigma_{y}\right)=\frac{1}{\sqrt{2 \pi} \sigma_{y}} \exp \left(-\frac{1}{2} \frac{(y-x)^{2}}{\sigma_{y}^{2}}\right)
\end{aligned}
$$

Choose values for $\mu \& \sigma$. Evaluate $p(x)$ and $p(y \mid x)$ over a grid of points $x$ and $y$ over appropriate ranges (so that $p(x)$ drops close to zero"within the grid). The matlab command meshgrid() may help. Treat the resulting probability and grid values as a discrete probability distribution, and construct probability tables for both distributions. The purpose is to approximate the continuous distributions by discrete distributions. Make sure the sum-to-1 constraints are satisfied. Using the discrete tables, use marginalization and Bayes' rule to compute the probability tables for $p(y)$ and $p(x / y)$.
4. $(15 \%)$ Generate a set of 100 random $x, y$ coordinates using rand(). Use scatter() to display them. All the points should live in the unit square. Let $s$ denote 1 point. Compute the average inner product of these points: $E\left[s^{T} \cdot s\right]=\frac{1}{100} \sum_{j=1: 100} S_{j}{ }^{T} \cdot S_{j}$. Transform each of these points by a matrix $Q=\left[\begin{array}{ll}0.7419 & 4.2243 \\ 0.7283 & -1.3573\end{array}\right]$, so that $z=Q \cdot s$. Scatterplot $z$. Compute the average inner product of the $z$ points. Use an eigenanalysis of Q to explain the difference between the $s$ and the $z$ lengths. Compute the area the transformed points live in using Q . Using the relationship $Q=A \Lambda A^{-1}$, (where $A$ contains the normalized eigenvectors and $\Lambda$ is a diagonal matrix of eigenvalues) to determine the transform executed by $A$. Use arrow() to plot the columns of A with the scatterplot of $z$. The net effect of $Q$ on the length of the vectors $s$ is a rotation and a scaling introduced by $Q^{T} Q$. Find the angle of the rotation executed by $Q^{T} Q$. Hint: do an eigenanalysis of $Q^{T} Q$, make sure the eigenvectors (e.g. A ) are length 1 and the eigenvector matrix has det of 1 (the det $=-1$, so you must fix it), then use the parametric form of a 2-D rotation matrix:
$R=\left[\begin{array}{cc}\cos (\theta) & -\sin (\theta) \\ \sin (\theta) & \cos (\theta)\end{array}\right]$.
5. $(15 \%)$ Compute the distribution of the sum of four fair 8 -sided dice.
6. $(20 \%)$ Below you will find 2 sets (A and B), each with 9 examples of patterns generated by some mysterious process, labeled training data. Below that you will find an additional set labeled test data.
TRAIN - Using only the training data, invent two different measurements on aspects of these patterns, and make these measurements on all the patterns (by a method of your choice - for example by hand with a ruler, via a graphics program, etc.). Try to choose measurements that help separate the classes. Call the first measurement type feature1, and the second feature2. Make a scatter plot of the feature 1 and feature2 values, using plot or scatter. Use different labels for class 1 and class 2. Determine a straight line in this space that appears to separate this data by eye.

Now determine the measurements on the TEST DATA, and plot the new feature vectors in the same plot (i.e. using the matlab command hold on), but using symbols that distinguish both class A and B and TEST points from TRAINING points. Determine the number of errors and the type of error (e.g. labeled A when actually B) for the TEST DATA using your line to classify. Submit the resulting image.










SET B









